

Solving Hybrid Boolean Constraints by Fourier Expansions and Continuous Optimization

Zhiwei Zhang's M.S. thesis defense – Computer Science Department

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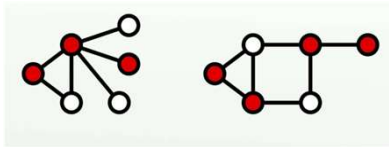
Anshumali Shrivastava

Background: SATisfiability Problem

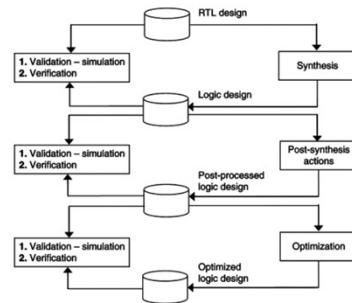
- Variables: $x, y, z \dots \in \{1, -1\} \quad \{F, T\}$
- Connectives: $\neg(Not), \wedge(and), \vee(or), \oplus(xor) \dots$
- Literals: $\neg x, y, \neg z \dots$
- Formula: $(x \wedge \neg y) \oplus z \dots$
- Solution: an assignment with -1/1s of variables s.t. formula yields -1
- SAT: Does a formula have a solution or not?
 - $x = -1(T), y = 1(F)$ is a solution of $x \wedge \neg y$ (SAT)
 - no solution exists for $x \wedge \neg x$ (UNSAT)
- NP-completeness of SAT was proven in 1971 by Stephen Cook

Applications of SAT

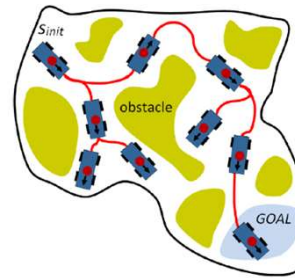
Used by hardware and software designers on a daily basis



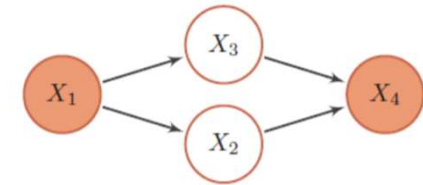
Discrete Optimization
[Ignatiev et al., 2017]



Software Verification
[Velev, 2004]



Motion planning
[Bera, 2017]



Probabilistic inference
[Chavira et al., 2008]

SAT solvers solve industrial SAT instances with **millions** of variables
[Katebi et al., 2011]

CNF and Hybrid SAT Solving

- Conjunctive Normal Form (CNF)
 - Connectives: $\neg, \wedge, \vee$
 - Clauses: $x_1 \vee x_2 \vee \neg x_3 \dots$
 - Formulas: $(x_1 \vee x_2 \vee \neg x_3) \wedge (x_2 \vee x_4) \dots$
 - 3-CNF is NP-complete [Cook, 1971]
- Non-CNF Clauses/Constraints
 - cryptography: XOR [Bogdanov et al., 2011]
 - graph theory: cardinality constraints [Costa et al., 2009]
not-all-equal (NAE) [Tomas J, 1978]

$$\begin{aligned} & x \oplus y \oplus z \\ & x + y + z \geq 2 \\ & NAE(x, y, z) = \neg(x = y = z) \end{aligned}$$

Related Work: Hybrid SAT Solving

- CNF-encoding of Non-CNF constraints

Involves large number of new variables and clauses [Wynn, 2018]

Encodings differ from size, arc-consistency and density of solutions [Prestwich 2009]

- Extensions of CNF solvers

Cryptominisat (CNF + XOR) [Soos et al., 2009]

Minicard (CNF + cardinality constraints) [Liffition et al., 2012]

MonoSAT (CNF + graph properties) [Bayless et al. 2015]

Pueblo (CNF + pseudo Boolean constraints) [Sheini et al., 2006]

Need to design algorithms for each specific type of constraints

Contribution: A versatile Boolean SAT Solver

$$f = c_1 \wedge c_2 \wedge \cdots \wedge c_m$$

Each c_i can be a CNF, XOR, Not-all-equal constraint or cardinality constraint

FourierSAT: A SAT solver based on gradient method to handle different types of constraints uniformly

Fourier Expansion of Boolean Function

Boolean formulas



Multilinear Polynomials

$$f : \{1, -1\}^n \rightarrow \{1, -1\}$$
$$\{F, T\}$$

$$p : \{1, -1\}^n \rightarrow \{1, -1\}$$

$$x \wedge y$$



$$\frac{1}{2} \cdot 1 + \frac{1}{2} \cdot x + \frac{1}{2} \cdot y - \frac{1}{2} \cdot xy$$

x	y	$x \wedge y$	$\frac{1}{2} + \frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}xy$
1	1	1	1
1	-1	1	1
-1	1	1	1
-1	-1	-1	-1

Fourier Expansion of Boolean Function

Boolean formulas  Multilinear Polynomials

Theorem

Given a Boolean function $f : \{-1, 1\}^n \rightarrow \mathbb{R}$, there is a unique way of expressing f as a multilinear polynomial:

$$f(x) = \sum_{S \subseteq [n]} \left(\hat{f}(S) \cdot \prod_{i \in S} x_i \right)$$

[O'Donnell, 2014]

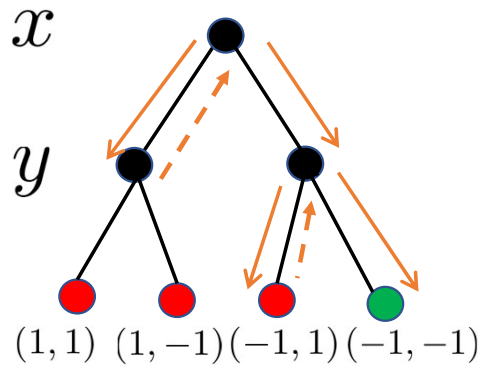
Fourier coefficients on S

multilinear monomials

$$x \wedge y \longrightarrow \left(\frac{1}{2}\right) \cdot 1 + \left(\frac{1}{2}\right) \cdot x + \left(\frac{1}{2}\right) \cdot y - \left(\frac{1}{2}\right) \cdot xy$$

From SAT to continuous optimization

$$x \wedge y$$

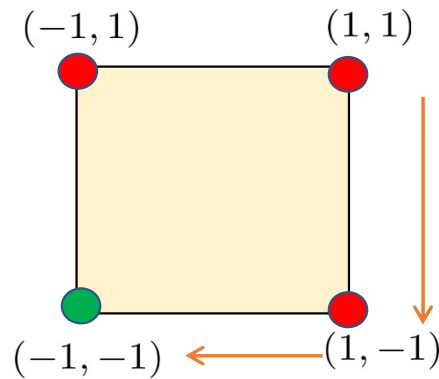


Tree Search/Backtracking
(DPLL/CDCL)

propagation
conflict analysis ...

variable selection heuristics

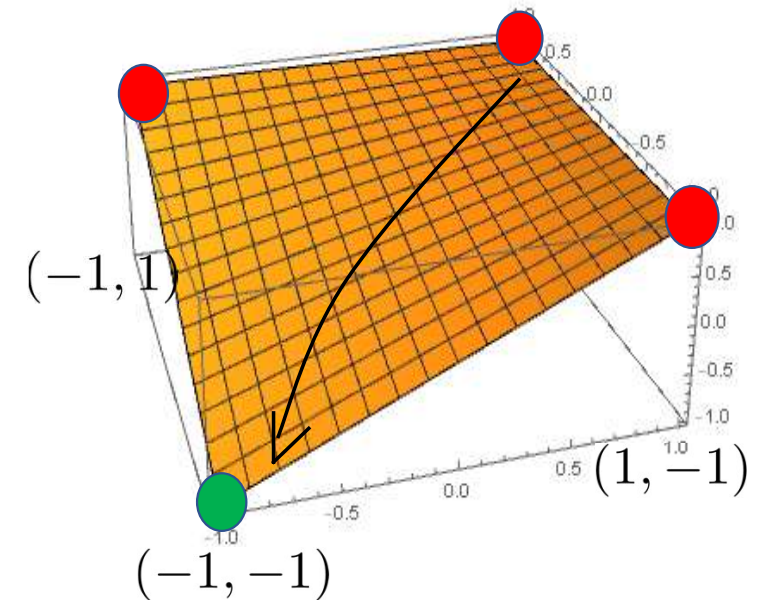
discrete searching on Boolean domain



Local Search

“sideway” walk
random walk ...

$$\frac{1}{2} + \frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}xy$$



formulas can be evaluate on reals

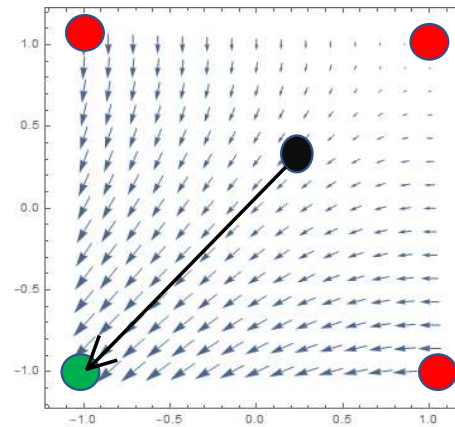
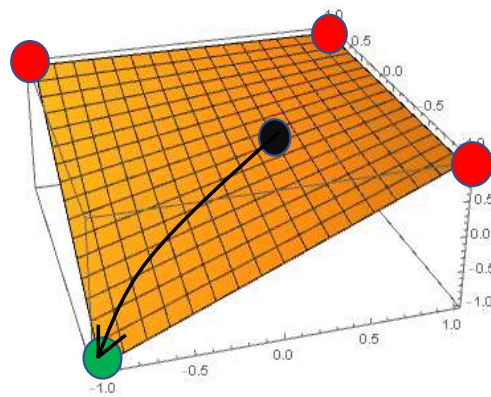
optimization on continuous domain

Approach: From SAT to Continuous Optimization

Discrete searching on
Boolean formulas



Continuous optimization on
multilinear polynomials



Let multilinear polynomial G be the Fourier transform of formula f

Theorem

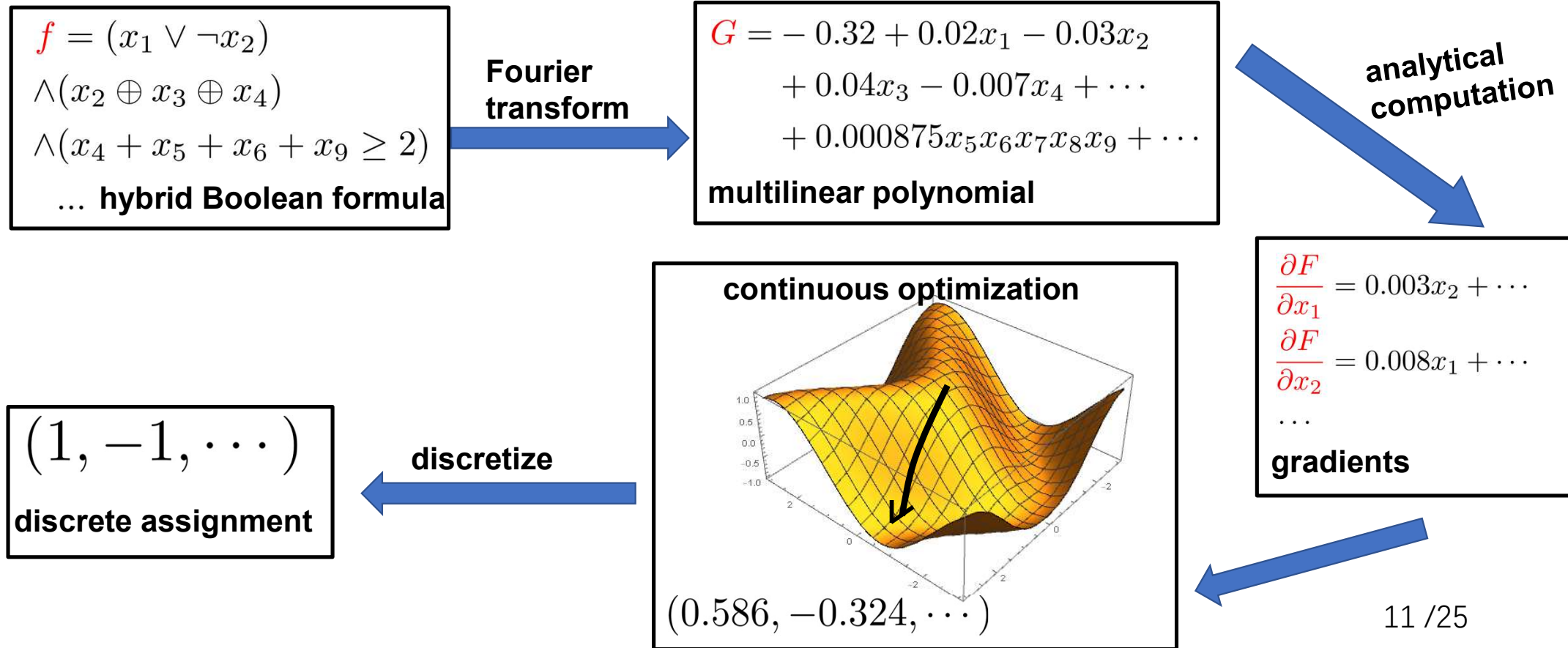
$$f \text{ is SAT} \Leftrightarrow \min_{x \in [-1, 1]^n} (G) = -1$$

Every local minimum of G in $[-1, 1]^n$ is global.

Workflow

Problems:

- Computing the Fourier Expansion of a Boolean function is #P-hard
- How to evaluate a polynomial with exponentially many terms?



Factored Representation

$$f = c_1 \wedge c_2 \wedge \cdots \wedge c_m$$

- Many symmetric constraints have closed form Fourier expansion

Type of Constraint	Example	Fourier Expansion
CNF clauses	$x \wedge y$	$\frac{1}{2} + \frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}xy$
XOR	$x \oplus y \oplus z$	$x \cdot y \cdot z$
Cardinality constraints	$x + y + z \geq 2$	$\frac{1}{2}x + \frac{1}{2}y + \frac{1}{2}z - \frac{1}{2}xyz$
Not-all-equal	$NAE(x, y, z)$	$-\frac{1}{2} + \frac{1}{2}xy + \frac{1}{2}yz + \frac{1}{2}xz$

Define a new objective function by the Fourier Expansion of each clause

$$f = c_1 \wedge c_2 \wedge \cdots \wedge c_m$$

$$F = p_1 + p_2 + \cdots + p_m$$

Fourier expansions

$$F = \sum_{i=1}^m p_i$$

Objective Function Construction

$$f = c_1 \wedge c_2 \wedge \cdots \wedge c_m$$

$$F = p_1 + p_2 + \cdots + p_m$$

$$F = \sum_{i=1}^m p_i$$

Fourier expansions

$$f = (x \vee \neg y) \wedge (x \oplus y)$$

$$\begin{aligned} F &= \left(-\frac{1}{2} + \frac{1}{2}x - \frac{1}{2}y - \frac{1}{2}x \cdot y\right) + (x \cdot y) \\ &= -\frac{1}{2} + \frac{1}{2}x - \frac{1}{2}y + \frac{1}{2}x \cdot y \end{aligned}$$

- Efficient Objective Function Evaluation

F can be evaluated in $O(k^2 \cdot m)$ time

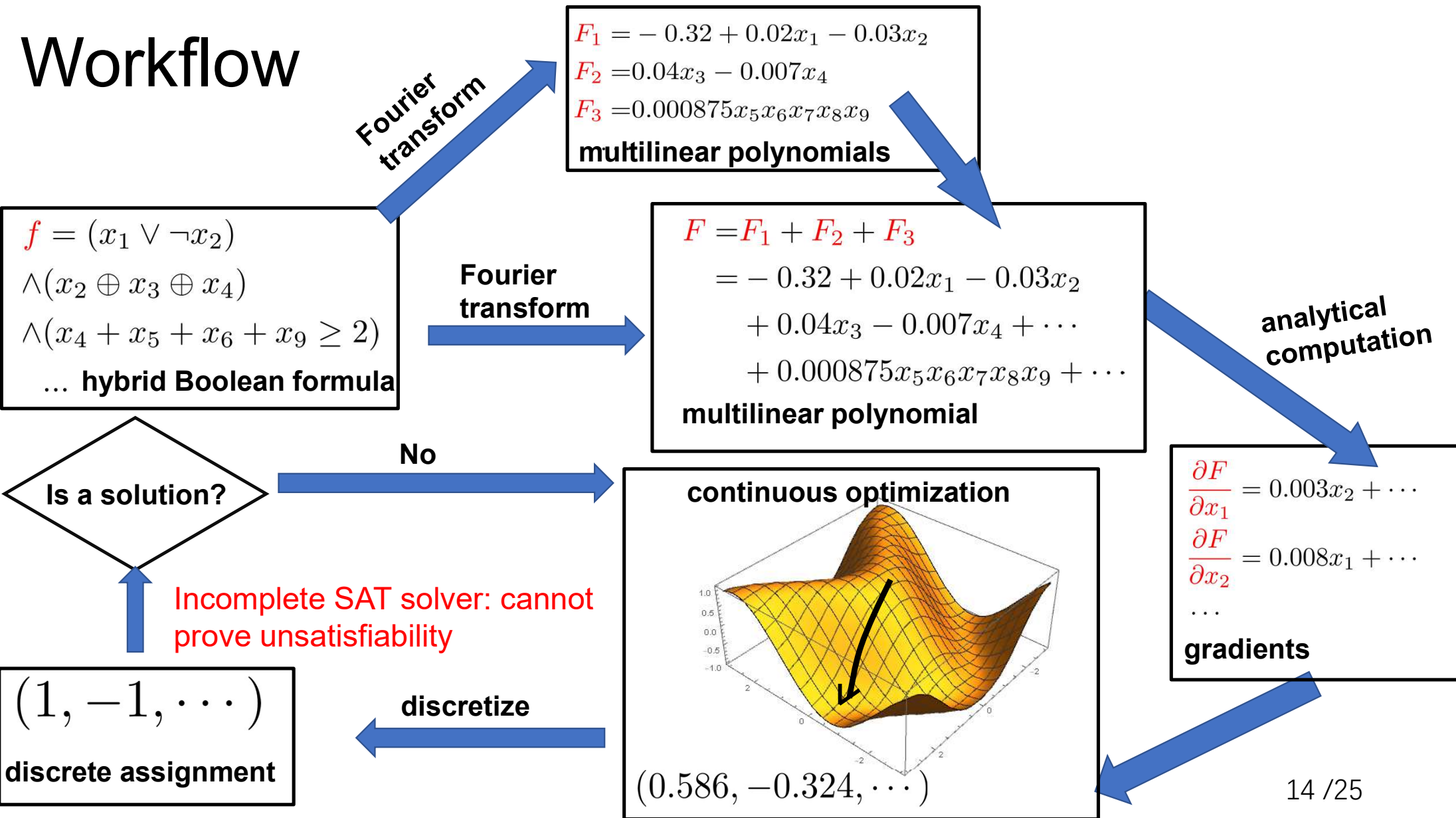
k --- maximum width of all clauses

m --- number of clauses

Theorem

$$f \text{ is SAT} \Leftrightarrow \min_{x \in [-1, 1]^n} (F) = -m$$

Workflow



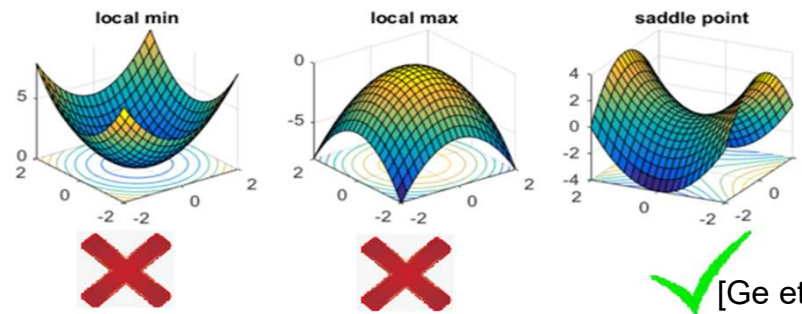
Multilinear Polynomials: Well-behaved

$$F = \sum_{i=1}^m p_i$$
$$f = c_1 \wedge c_2 \wedge \cdots \wedge c_m$$
$$F = p_1 + p_2 + \cdots + p_m$$

Bounded: $p_i \in [-1, 1]$ and $F \in [-m, m]$ for every $x \in [-1, 1]^n$

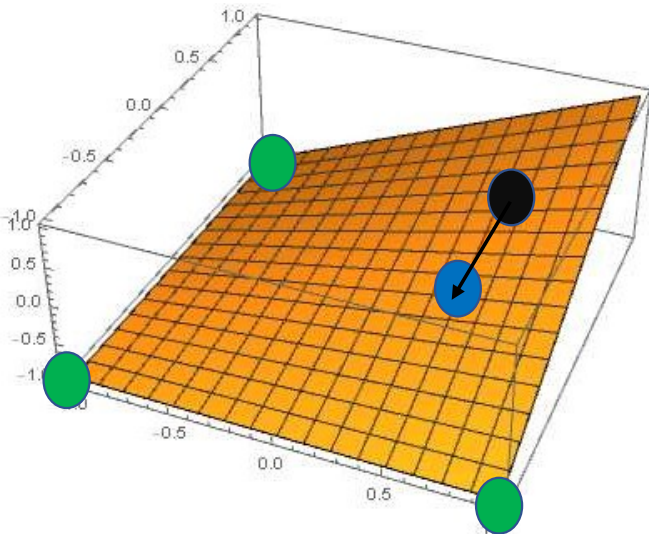
Theorem (Saddle Landscape)

At every $x \in \mathbb{R}^n$, $\exists$ a decreasing direction v and $\epsilon > 0$, $F(x + \epsilon v) < F(x)$



[Ge et al., 2016]

What does the Objective Function Value Indicate?



Theorem

$F(x) = -k \Rightarrow \frac{m+k}{2}$ clauses can be satisfied in expectation

Making “small” progress in expectation per iteration

Randomized Rounding:

$$P[R(x)_i = -1] = \frac{1}{2} - \frac{1}{2}x_i$$

$$P[R(x)_i = 1] = \frac{1}{2} + \frac{1}{2}x_i$$

MAXCUT Relaxations

- LP relaxation: $\frac{3}{4}$ -approximate—25% loss
- SDP relaxation: 0.878-approximate—13.2% loss
- ”Fourier relaxation”: no loss

Why Not Just Do Discrete Local Search?

Greedy Local Search Solver (GSAT) [Selman et al., 1992]: per iteration, flip a bit to maximize the number of satisfied clauses

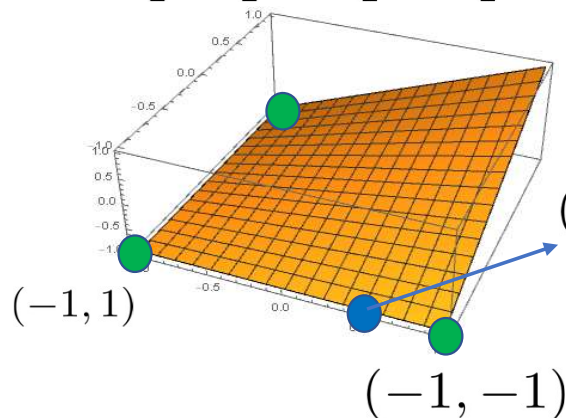
$$x_1 + x_2 + \cdots + x_{100} \geq 70, x_i \in \{0, 1\}$$

start from $|x| = 50$  Need to flip at least 20 bits

GSAT will not make progress for a long time!

Local Minimum is “almost integer”

$$F = -\frac{1}{2} + \frac{1}{2}x + \frac{1}{2}y + \frac{1}{2}xy \quad (x \vee y)$$



$$(-1, 0.5) \longrightarrow F(-1, 0.5) = F(-1, 1) = F(-1, -1)$$

Local minimum

Theorem

Every local minimum x of F can be discretized to x^* with $F(x^*) = F(x)$

$$F(x) = -k$$

(Deterministically)

$\Rightarrow \frac{m+k}{2}$ clauses can be satisfied

x is a local minimum

Projected Gradient Descent Converges Fast

Multilinear polynomials are smooth:

For $F \in [-\alpha, \alpha]$ and $x, y \in [-1, 1]^n$

Lipschitz continuous:

$$|F(x) - F(y)| \leq \alpha\sqrt{n} \cdot \|x - y\|_2$$

Lipschitz gradient:

$$\|\nabla F(x) - \nabla F(y)\|_2 \leq \alpha n \cdot \|x - y\|_2$$

if f is k -SAT $\alpha\sqrt{k}$

αk

Theorem

For a formula with n variables and m clauses, Projected Gradient Descent converges to a ϵ -projected-critical point in $O(\frac{nm^2}{\epsilon^2})$

$$O(\frac{km^2}{\epsilon^2})$$

Implementation Techniques

- Weighted version:

$$F = \sum_{i=1}^m p_i \longrightarrow F = \sum_{i=1}^m w_i \cdot p_i$$

- Analytical Gradient Computation

Feeding gradient to optimizer significantly accelerated the algorithm

- Random Restart and Parallelization

Different trials are independent so that parallelization is easy

- Fast computation of gradient and function value

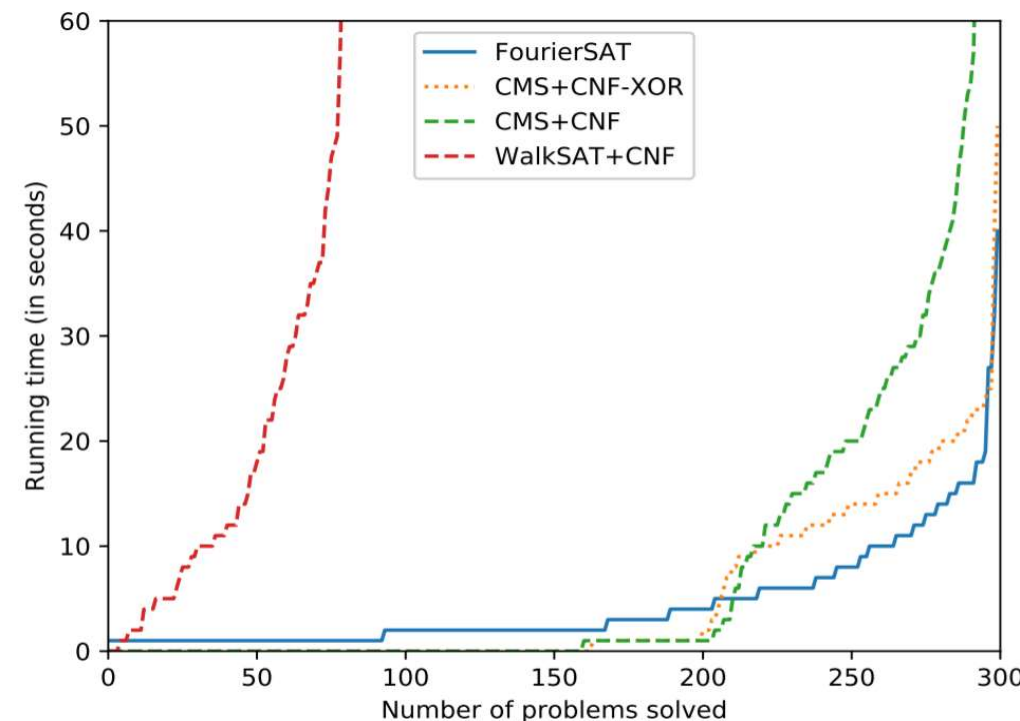
$$F\{x_1 \vee x_2 \vee x_3\}(-1, 0.345, -0.474) = -1$$

Benchmark 1: Parity Learning with Errors

- Solving a random XOR system of m XOR equations and n variables but tolerating up to $e \cdot m$ equations to be violated
- $e = 0$: Gaussian Elimination (P)
 $m > n$: UNSAT w.h.p
- $e > 0$: whether in P is still open
- $m = 2n$, $e = \frac{1}{4}$: Known as hard instances for both DPLL and local search SAT solvers
- XORs + 1 Cardinality Constraint

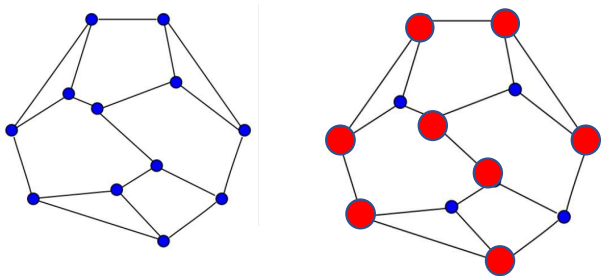
$$\begin{aligned} x_1 \oplus x_2 \oplus x_3 &= -1 \\ x_1 \oplus x_2 &= -1 \\ x_2 \oplus x_3 &= -1 \\ x_1 \oplus x_3 &= -1 \end{aligned}$$

UNSAT for $e = 0$. SAT for $e = 0.25$

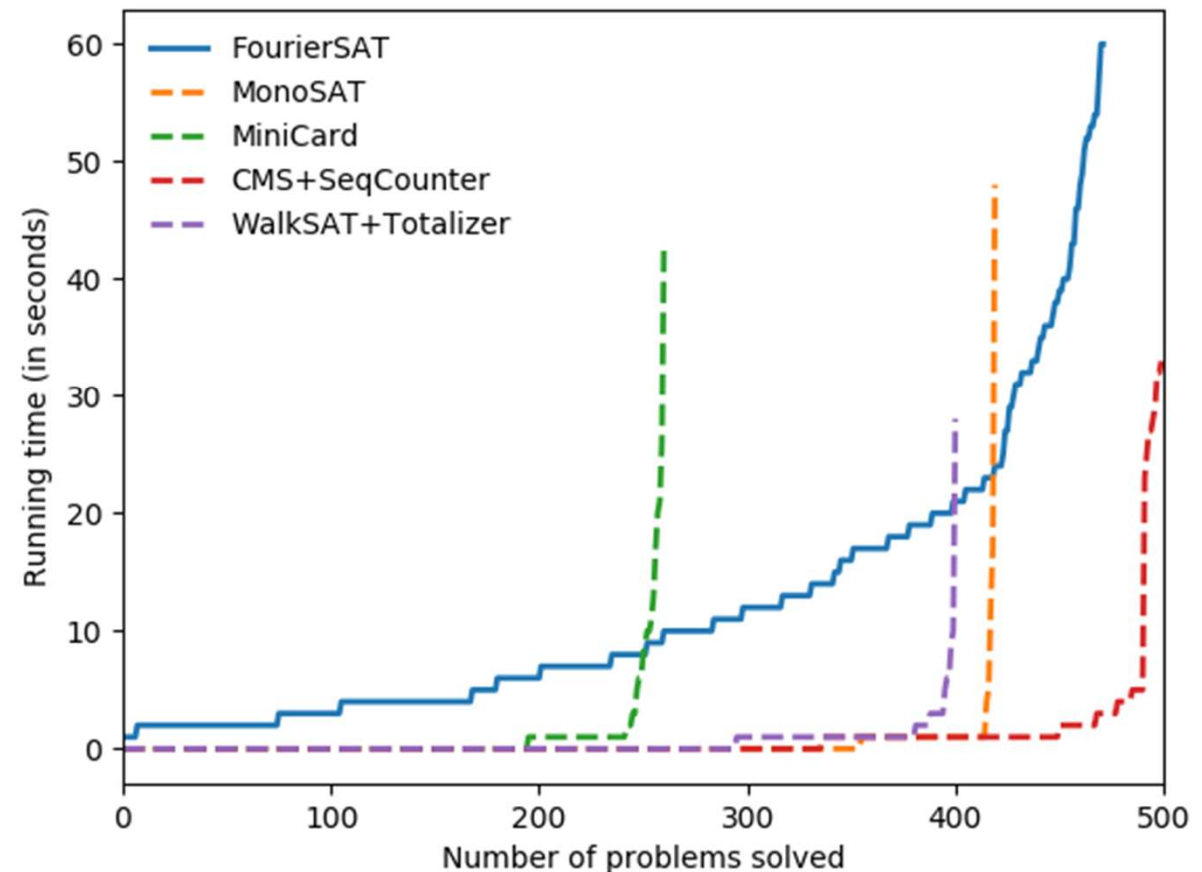


Benchmark 2: Approximate Minimum Vertex Covering

- Finding a vertex set Sol of random cubic graphs s.t. $|Sol| \leq 1.1 \cdot |Opt|$



- CNFs + 1 global cardinality Constraint



Benchmark 3: MaxSAT

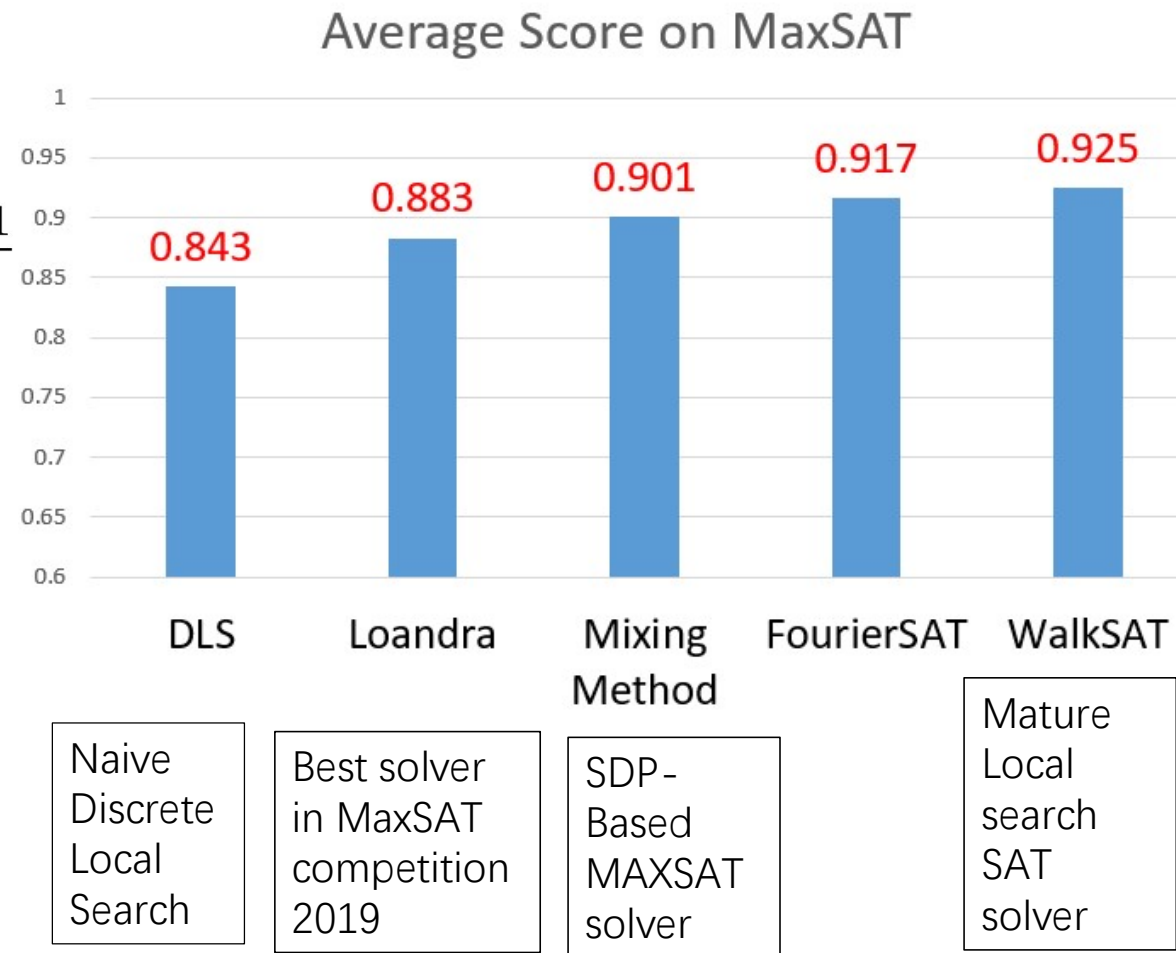
- MaxSAT: solving UNSAT instances with as few violated clauses as possible

For a solver i on instance j

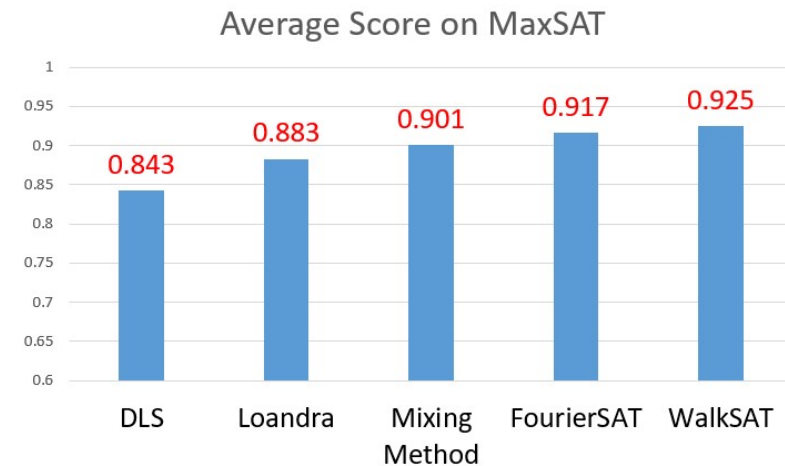
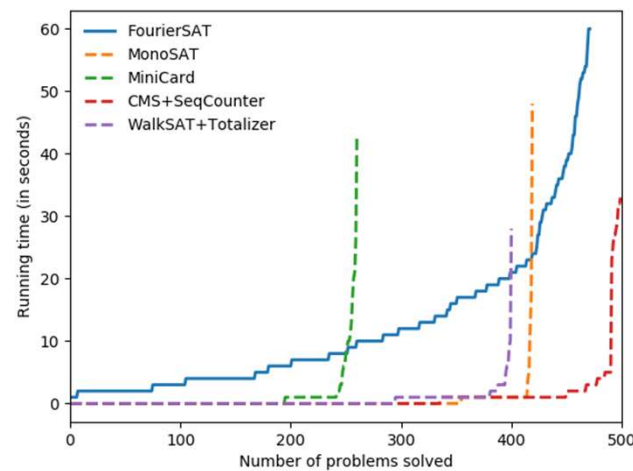
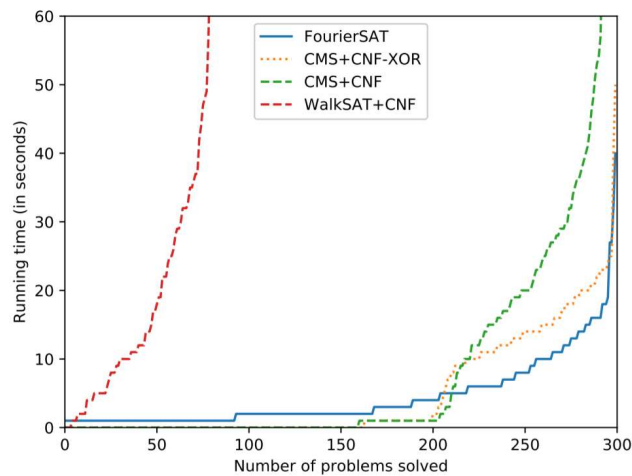
$$S_{ij} = \frac{(\text{least \#violated clauses by all solvers})+1}{(\text{\#violated clauses by solver } i)+1}$$

Solver	A	B	C	D
# violated clauses	2	3	10	6
Score	1	0.75	0.27	0.43

- Relatively small benchmarks form MAXSAT competition 2016



FourierSAT is Versatile and Shows Great Potential



- FourierSAT is comparable with state-of-the-art SAT/MaxSAT solvers even without lots of engineering

Conclusion

- SAT solving beyond CNF is worth studying
- Our work, FourierSAT is a versatile and robust tool for Boolean SAT
- Applications of Fourier analysis and other algebraic techniques for Boolean logic are promising
 - Bridging discrete and continuous optimization
- Future directions:
 - Proving unsatisfiability algebraically
 - Deploying FourierSAT with methods from local search SAT solvers
 - Alternative object function: approximate, efficient gradient